



Footfall Induced Vibration

Arup Unified Method for Floors, Footbridges, Stairs and Other Structures

Ben Sitler, PE



Outline

- Introduction to Footfall Induced Vibration
- Computing the Structural Response
- Project Examples
- References

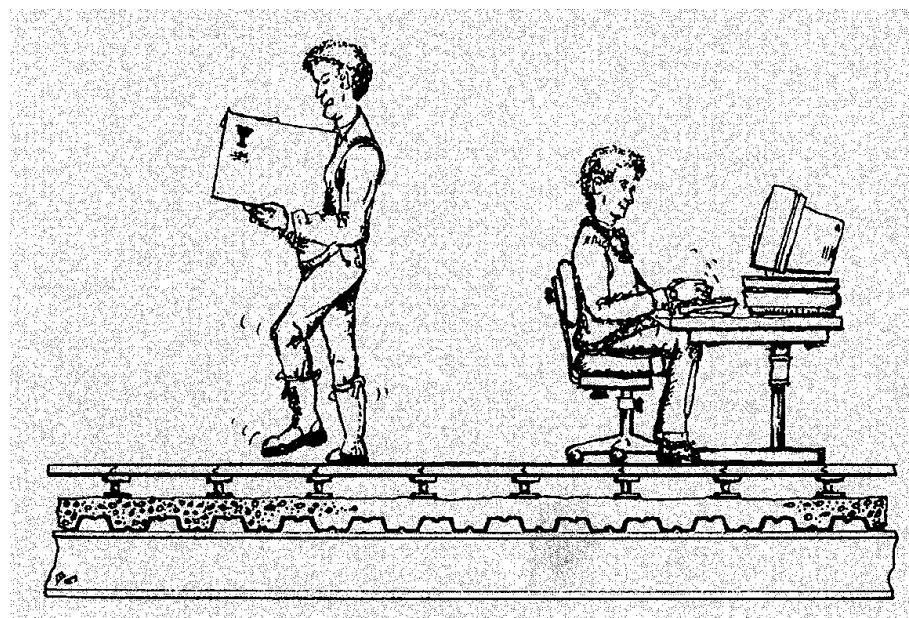


Introduction to Footfall Induced Vibration

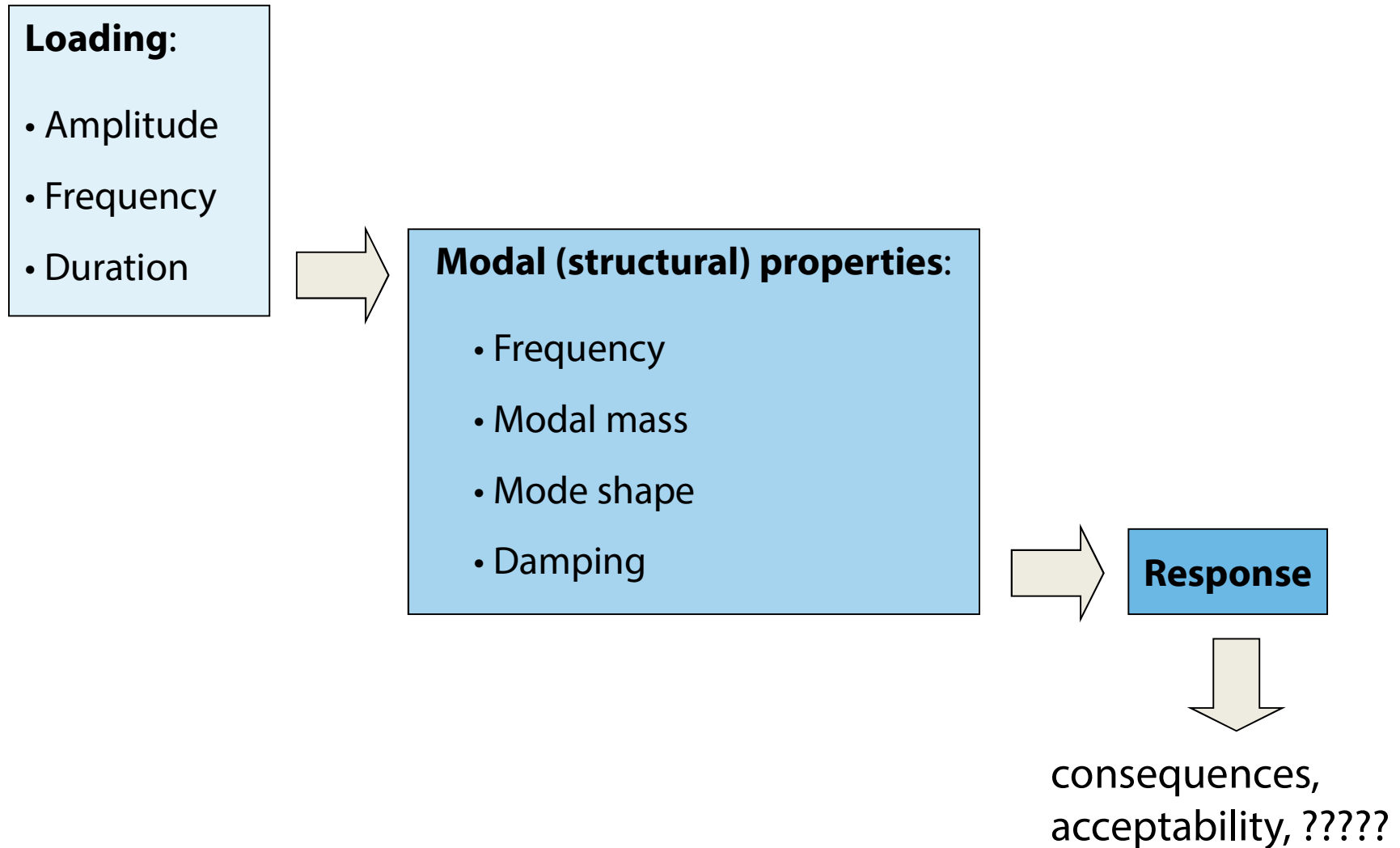
When is footfall induced vibration an issue?



- Low **Frequency** (Resonance)
- Low **Mass** ($Acc=Force/Mass$)
- Low **Damping**
- Large Dynamic Loads (Crowds)

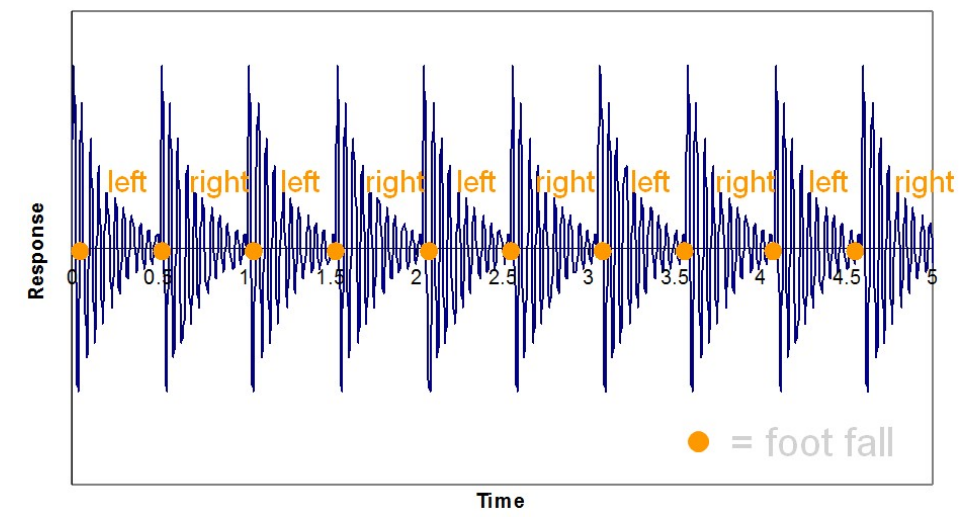
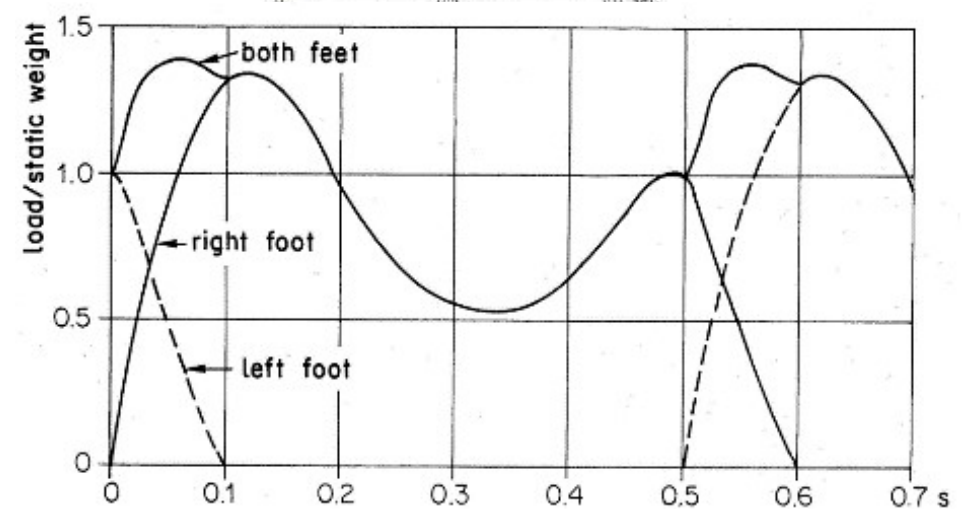
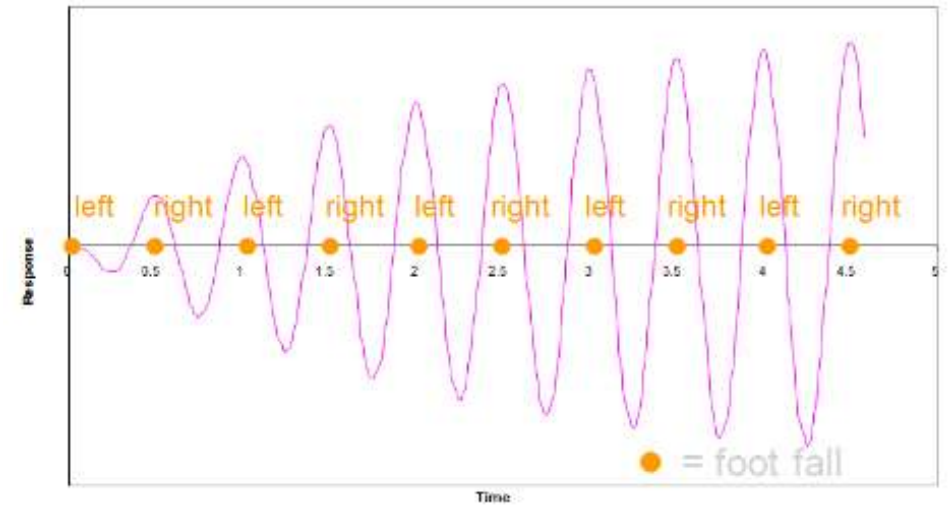
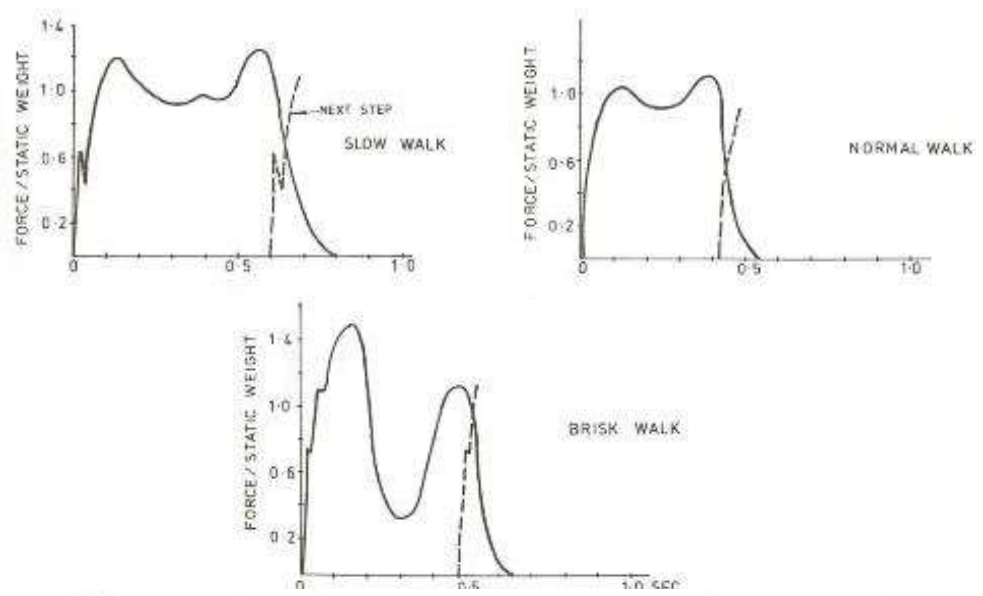


The design problem





What does a footfall time history look like?

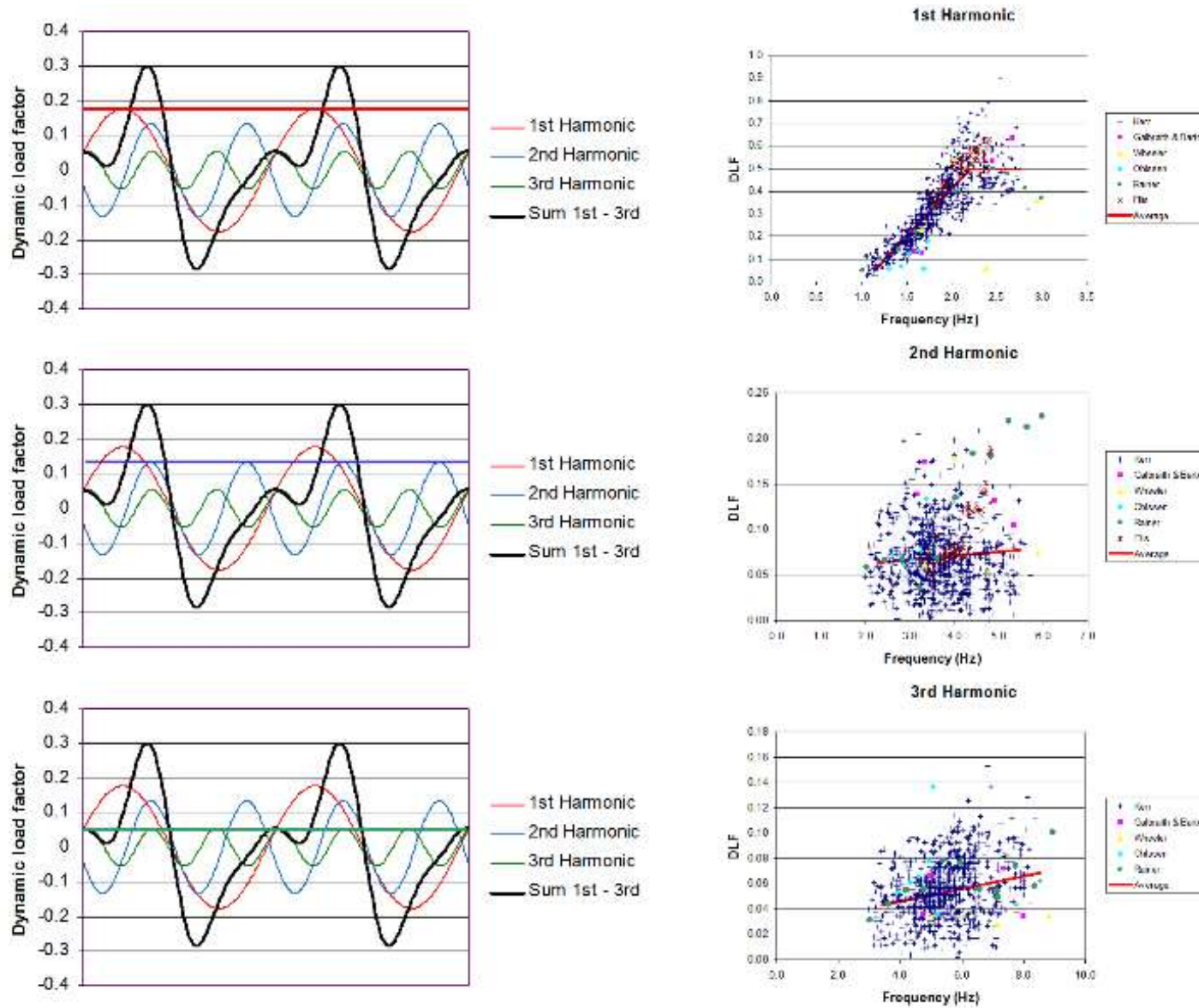




What kinds of excitation frequencies are possible?



So how does this translate into a design load?





What is an appropriate amount of damping?

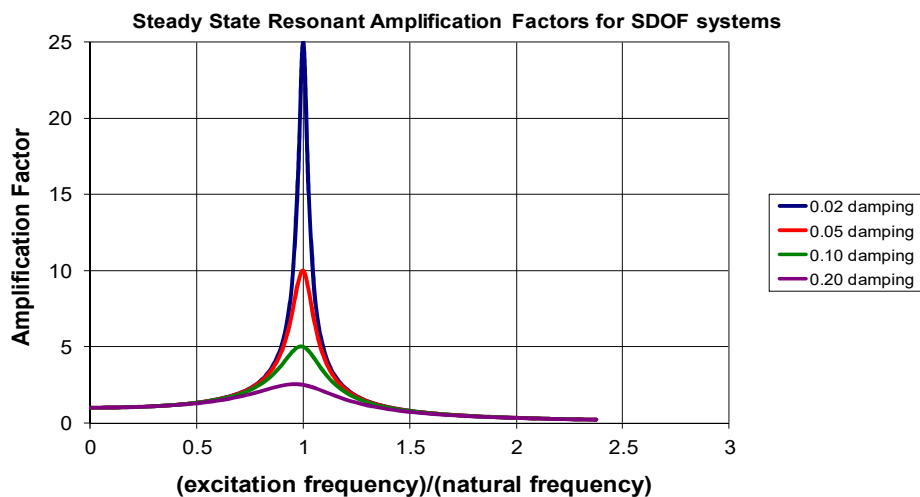
Damping :: Frequency :: Modal Mass :: Mode Shape

Be suspicious of >2%

Footbridges 0.5~1.5%

Stairs 0.5%

Floors 1~3%





Modelling Assumptions

Damping :: **Frequency** :: **Modal Mass** :: **Mode Shape**

...some tips (not exhaustive)...

Loads

- Use best estimate, not code values
- LL: ~0.5kPa typically realistic
- SDL: upper/lower bound sensitivity study

Model Extent

- Typically model single floor only
- Floorplate should capture all modes of interest

Boundary Conditions

- Fixed connections/supports unless true pin
- Façade vertical fixity may/may not be appropriate

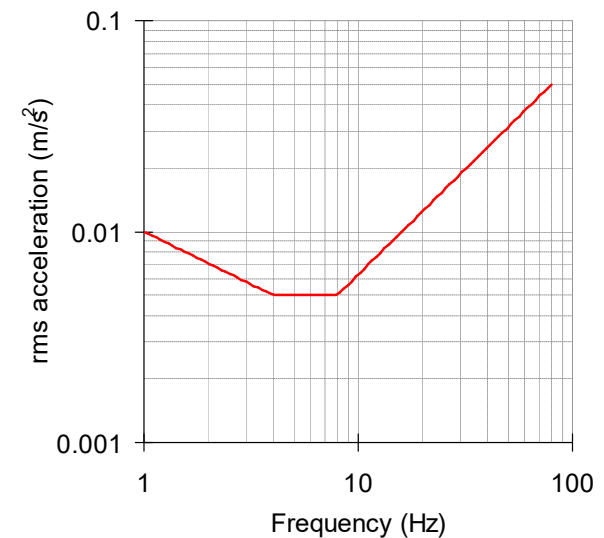
Member Modelling

- Orthotropic slab properties
- Composite beam (even if nominal studs)
- $E_{c,dynamic} \approx 38\text{GPa}$
- Subdivide 6+ elements per span

What is a good design criteria?

Situation	R	RMS Acc @ 5Hz
Low vibration	1	0.005 m/s ²
Residential (night)	1.4	0.007 m/s ²
Residential (day)	2-4	0.01~0.02 m/s ²
Office (high grade)	4	0.02 m/s ²
Office (normal)	8	0.04 m/s ²
Footbridge (heavy)	24	0.12 m/s ²
Footbridge (inside)	32	0.16 m/s ²
Footbridge (outside)	64	0.32 m/s ²
Stair (high use)	24	0.12 m/s ²
Stair (light use)	32	0.16 m/s ²
Stair (very light use)	64	0.32 m/s ²

Approximate threshold of human perception to vertical vibration



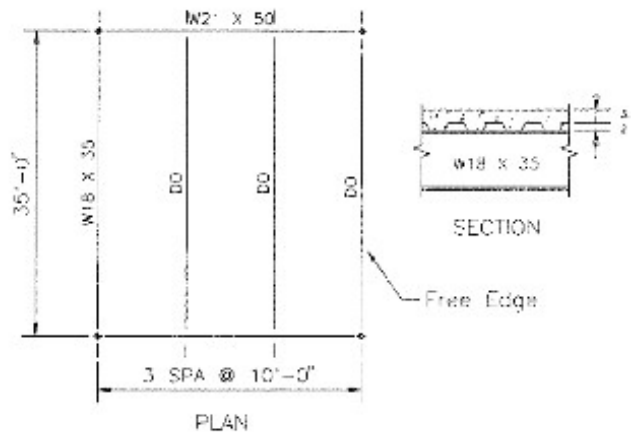
$$R = \frac{\text{Acc}_{\text{RMS}}}{\text{Acc}_{\text{RMS}}}$$

$$\text{Acc}_{\text{RMS}} = \sqrt{\frac{\sum_t^T \text{Acc}_t^2}{T}} = \frac{\text{Acc}_{\text{Peak, Harmonic}}}{\sqrt{2}}$$



Computing the Structural Response

Simplified vs Modal vs Time History Methods



VS

Modal harmonic response method

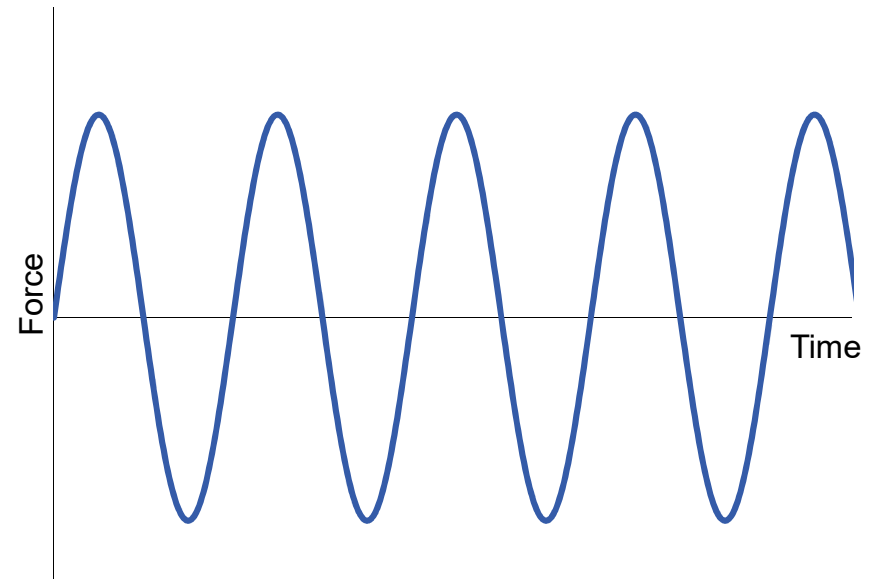
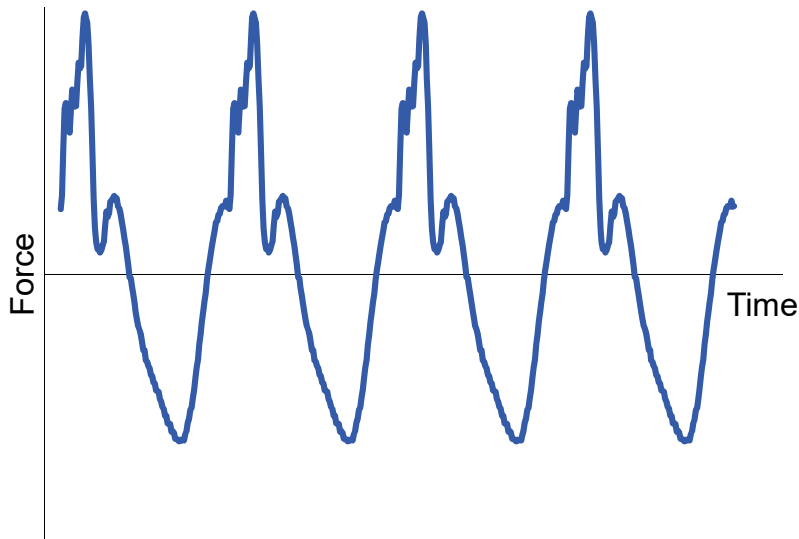
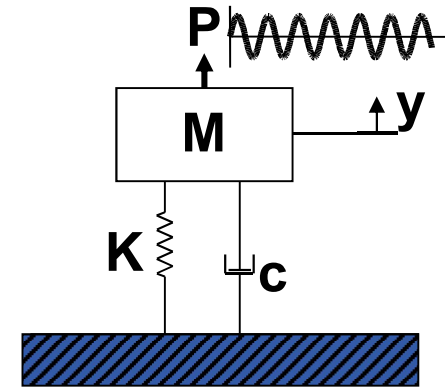
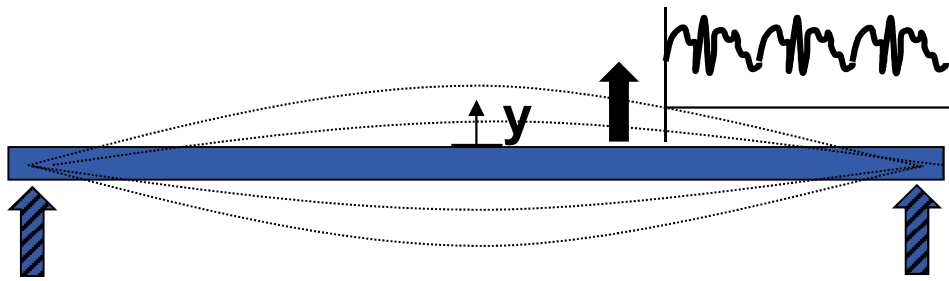
Typically $f = \frac{18}{\sqrt{y}}$ for most structures Where: f is in cycles per second
 y is the static deflection in mm

	Simply supported Mass concentrated in centre	$f = \frac{15.8}{\sqrt{y}}$
	Simply Supported Mass and stiffness distributed	$f = \frac{18}{\sqrt{y}}$
	Cantilever Mass concentrated at end	$f = \frac{15.8}{\sqrt{y}}$
	Cantilever Mass and stiffness distributed	$f = \frac{19.7}{\sqrt{y}}$

VS

Explicit time history method

Analytical Model



Resonant Response

SDOF Harmonic Steady State Response

$$m\ddot{y}(t) + c\dot{y}(t) + ky(t) = P(t) = P \cdot e^{i\omega t}$$

$$FRF_{disp} = \frac{1}{k - m\omega^2 + i c\omega} = \frac{1/k}{\left(1 - \left(\frac{f_h}{f_m}\right)^2\right) + i 2\xi \frac{f_h}{f_m}}$$

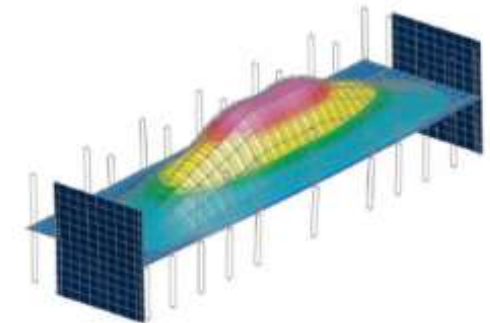
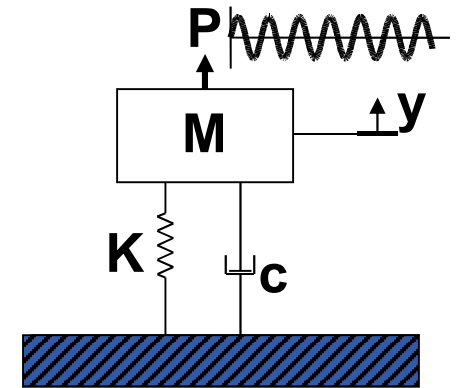
$$= \frac{\left(\frac{f_h}{f_m}\right)^2 \cdot \left(1 - \left(\frac{f_h}{f_m}\right)^2\right)}{\left(1 - \left(\frac{f_h}{f_m}\right)^2\right)^2 + \left(2\xi \frac{f_h}{f_m}\right)^2} + i \frac{\left(\frac{f_h}{f_m}\right)^2 \cdot 2\xi \frac{f_h}{f_m}}{\left(1 - \left(\frac{f_h}{f_m}\right)^2\right)^2 + \left(2\xi \frac{f_h}{f_m}\right)^2}$$

$$F = W \cdot DLF(f, harmonic)$$

$$Acc = \frac{\rho \cdot F \cdot \varphi_{excitation} \cdot \varphi_{reponse}}{m} \cdot FRF_{acc}$$

...Concrete Centre eq 4.4

f_h = harmonic forcing freq.
 f_m = modal (structural) freq.



Transient Response

SDOF Impulse – RMS Velocity Response

$$m\ddot{y}(t) + c\dot{y}(t) + ky(t) = P(t) = P \cdot e^{i\omega t}$$

$$I_{eff} = 54 \frac{f_w^{1.43}}{f_n^{1.3}} [\text{Ns}]$$

$$Vel_{Peak} = \frac{I_{eff} \cdot \varphi_{excitation} \cdot \varphi_{reponse}}{m}$$

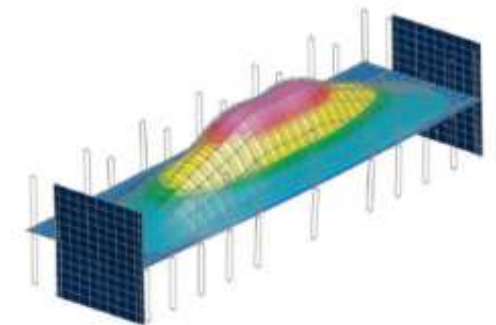
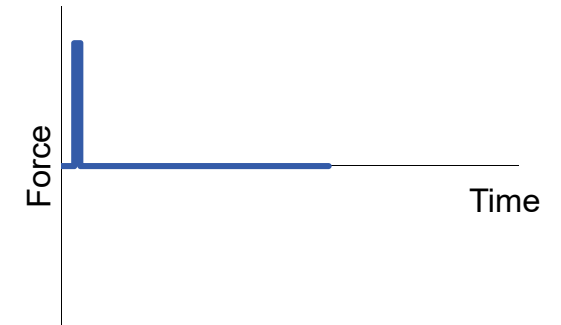
$$Vel(t) = Vel_{Peak} \cdot e^{-\omega \zeta t} \sin \omega t$$

$$Vel_{RMS} = RMS(\sum Vel(t)_m)$$

...Concrete Centre eq 4.10~4.13

f_w = walking forcing freq.

f_m = modal (structural) freq.





'Bobbing' Resonant Response

MDOF Harmonic Response – crowd interacting with structure

$$M\ddot{y}(t) + C\dot{y}(t) + Ky(t) = P(t) = P \cdot e^{i\omega t}$$

$$\begin{bmatrix} m_s & 0 & 0 \\ 0 & m_a & 0 \\ 0 & 0 & m_p \end{bmatrix} \begin{bmatrix} \ddot{y}_s \\ \ddot{y}_a \\ \ddot{y}_p \end{bmatrix} + \begin{bmatrix} c_s + c_a + c_p & -c_a & -c_p \\ -c_a & c_a & 0 \\ -c_p & 0 & c_p \end{bmatrix} \begin{bmatrix} \dot{y}_s \\ \dot{y}_a \\ \dot{y}_p \end{bmatrix} + \begin{bmatrix} k_s + k_a + k_p & -k_a & -k_p \\ -k_a & k_a & 0 \\ -k_p & 0 & k_p \end{bmatrix} \begin{bmatrix} y_s \\ y_a \\ y_p \end{bmatrix} = \begin{bmatrix} -P \\ P \\ 0 \end{bmatrix}$$

$$FRF_{disp} = \frac{1}{K - M\omega^2 + iC\omega} = \begin{bmatrix} k_s + k_a - \omega^2 m_s + i\omega(c_s + c_a) & -k_a - i\omega c_a \\ -k_a - i\omega c_a & k_a - \omega^2 m_a + i\omega c_a \end{bmatrix}^{-1}$$

$$DMF_{disp} = FRF(1,1) - FRF(1,2) = \frac{-\omega^2 m_a}{|FRF|} = \frac{1}{k_a D_a + \left(\frac{f}{f_a}\right)^2 - k_s \left(\frac{f_a}{f}\right)^2 D_a D_s}$$

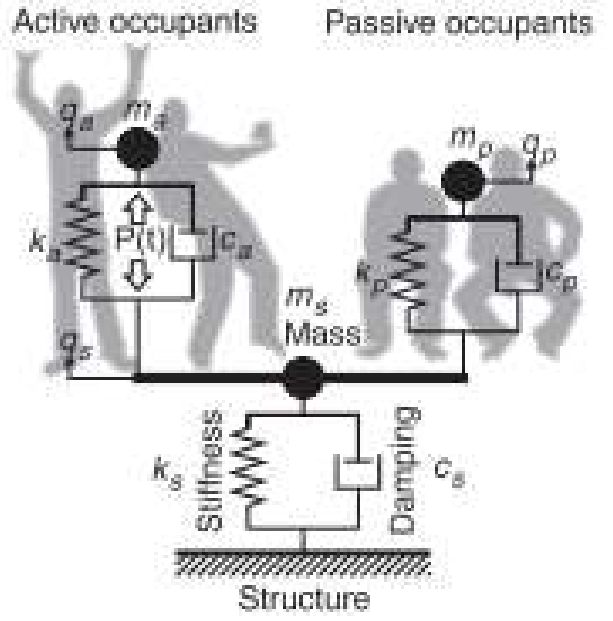
$$D_a = 1 - \left(\frac{f}{f_a}\right)^2 + i2\xi_a \frac{f}{f_a} \quad D_s = 1 - \left(\frac{f}{f_s}\right)^2 + i2\xi_s \frac{f}{f_s}$$

$$P = \rho(f) \cdot W_a \cdot GLF(\text{harmonic, scenario})$$

$$Acc = P \cdot \omega^2 DMF_{disp}$$

a = active crowd
 p = passive crowd
 s = structure

...IStructE Route 2



The Institution of Structural Engineers
 The Department for Communities and Local Government
 The Department for Culture Media and Sport
 December 2008

Dynamic performance requirements for permanent grandstands subject to crowd action

Programming Implementation

```

foreach node
  // Get response of governing excitation frequency
  RNode = MAX(RNode(f))
  foreach excitation frequency
    // Get R Factor
    RNode(f) = ACCRMS,Node(f) / ACCRMS,θ(f)
    // Get SRSS acceleration
    ACCRMS,Node(f) = √(∑Mode∑HarmonicACCRMS(n,m,h,f*h)2)
    foreach mode
      // Get modal properties
      // modal frequency (f), damping (ξ) & mass (m)
      // displacement at excitation(φne) & response(φnr) nodes
      // <participation factor(ρm)>, <static mass (W)>
      fm, ξm, mm, φne, φnr, Wm, ρm = ...
      foreach harmonic
        // Get harmonic properties
        // dynamic amplification factor(DLF), harmonic freq (f)
        DLFf,h, fm,h = ...
        // Get RMS acceleration
        ACCRMS(n,m,h,f*h) = RMS(F(fm,h, ξm, mm, φne, φnr, DLFf,h, Wm, ρm))

```

...Excel VBA is single threaded so no parallel processing
 ...Suggest building with parallel libraries in C#, VB, Python, etc

Library floor GSA model

2000 nodes x 20 modes x 4 harmonics x 1.5Hz
 frequency range = **2.4E7** calculations

Footbridge GSA model

6000 nodes x 40 modes x 2 harmonics x 6Hz
 frequency range (running) = **2.8E8** calculations

...not practical back in '90s, hence the simplified
 methods in AISC DG11, AS 5100-2, etc



Some Examples



How can we improve response?

- Increase Damping
- Increase Frequency
 - Increase Stiffness
 - Decrease Mass
- Increase Mass
- Isolate



Further Reading

General Structures (Vertical Resonant or Transient of Pedestrians)

- Concrete Centre CCIP-016 *A design guide for Footfall Induced Vibration of Structures*
- SCI P354 *Design of Floors for Vibration*

Stadia & Concert Hall (Vertical Resonance of Bobbing Crowd)

- IStructE *Dynamic Performance Requirements for Permanent Grandstands Subject to Crowd Action*
- C. Jones, A. Pavic, P. Reynold, R. Harrison *Verification of Equivalent Mass-Spring-Damper Models for Crowd-Structure Vibration Response Prediction*

High Use Footbridges (Lateral Synchronous Lock in and Vertical Crowd)

- P. Dallard *The London Millenium Footbridge*
- BSI PD 6688-2:2011 *Background to National Annex to BS EN 1991-2: Traffic loads on bridges*
- Setra *Footbridges: Assessment of Vibrational Behaviour of Footbridges under Pedestrian Loading*

contact: sitler.b.aa@m.titech.ac.jp